



# TagBreathe: Monitor Breathing with Commodity RFID Systems

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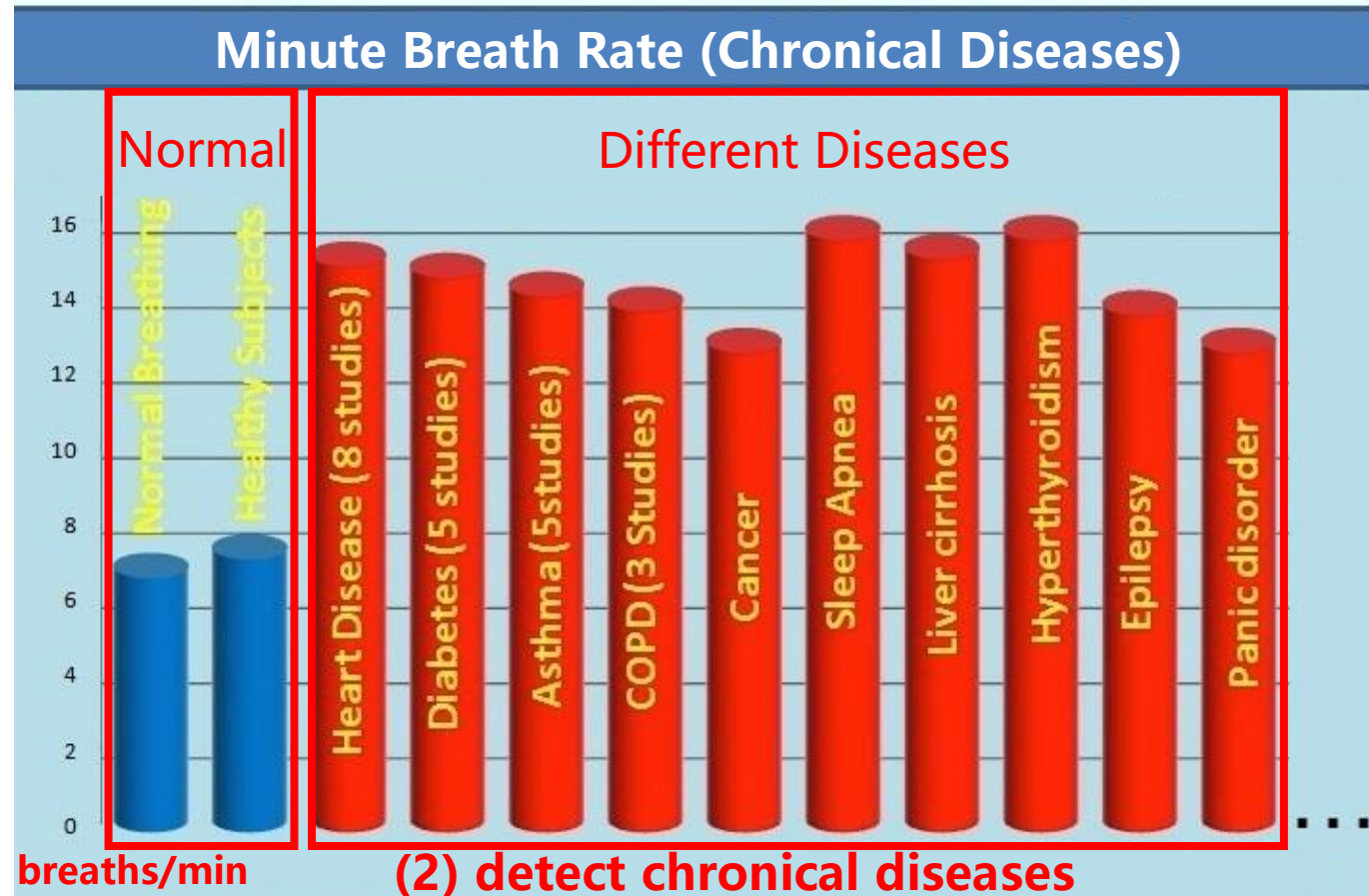
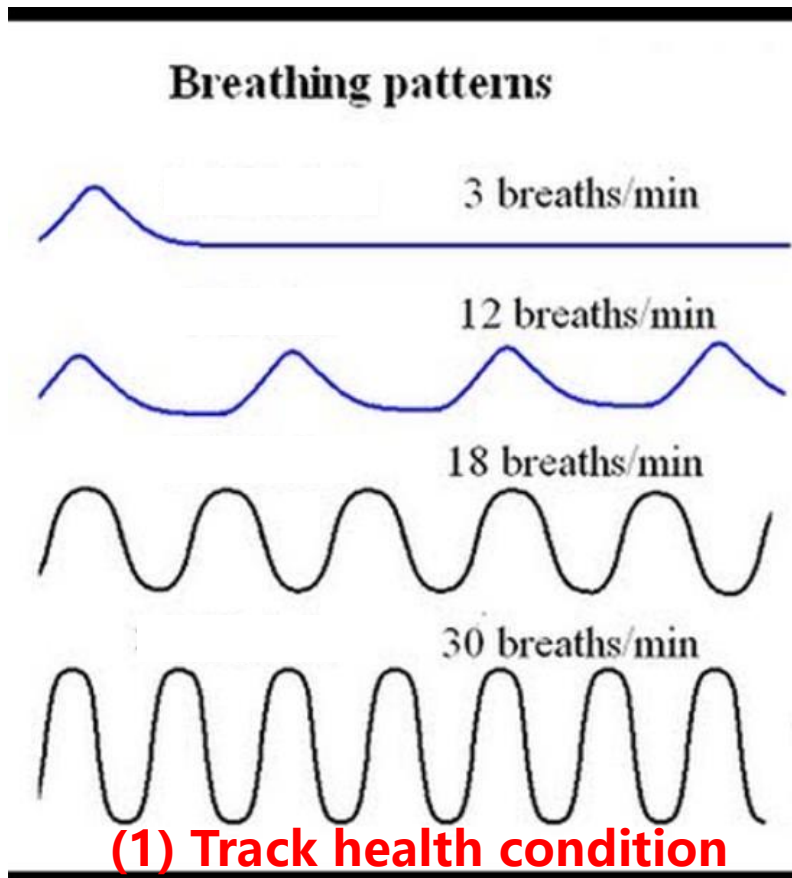
# Content

- Importance of Human Respiration Monitoring
- Background and Related Work
- The *TagBreathe* System
- Implementation & Evaluation
- Conclusion



# Importance of Human Respiration Monitoring

Medical evidence suggests that sick people are heavy breathers. Respiration rates are different for different diseases.





# Human Respiration Monitoring in Hospital

Respiration is a key index of human health



**intrusive & inconvenient !**





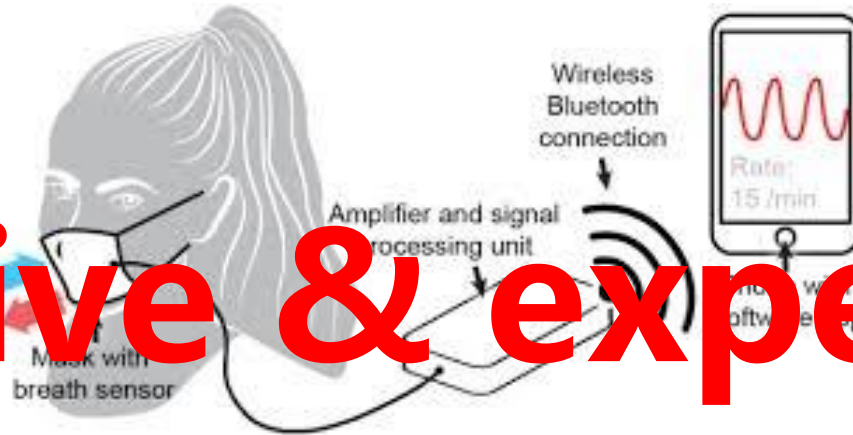
# Current Industry Products

## • Industry

Respiration Monitor Belt



Respiration Monitor Mask



Abdomen Respiration Sensor



Vital Sign Monitor



Respiration Monitor Probe



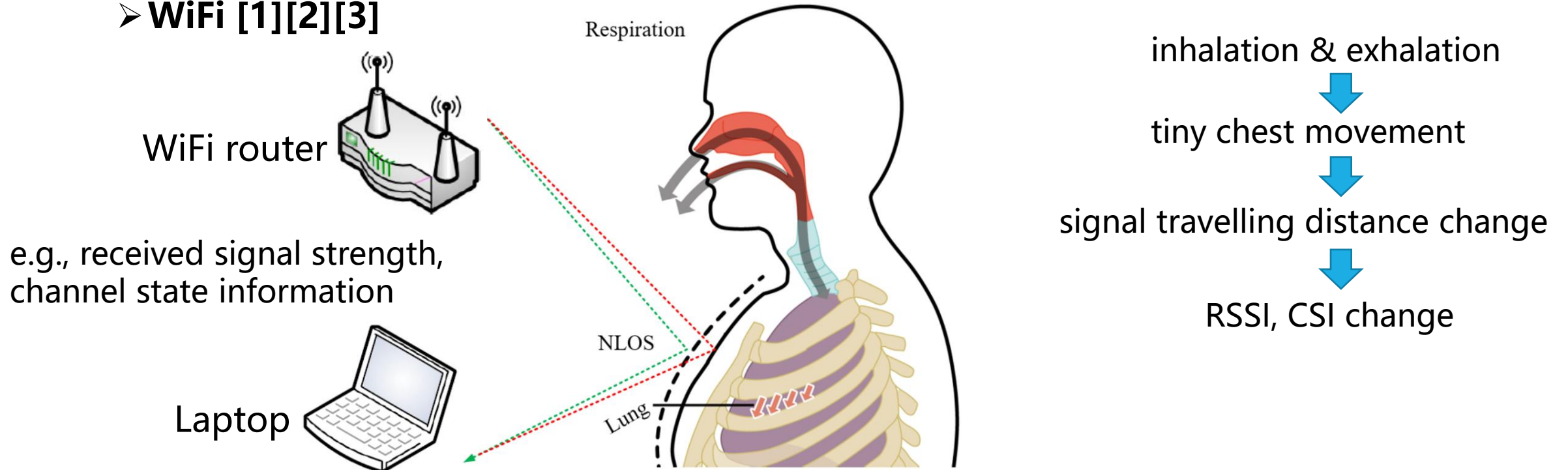
**intrusive & expensive!**

# Related Work

- **Research**

- **RF signal based respiration monitoring**

- **WiFi [1][2][3]**



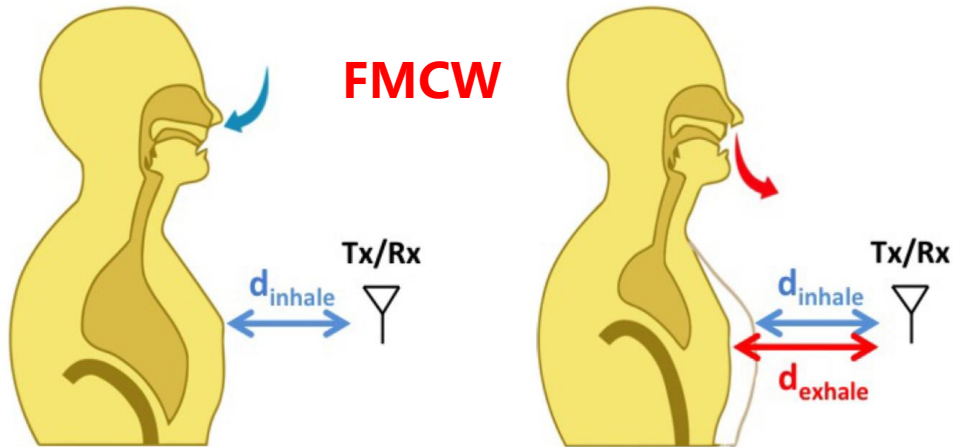
1. H. Abdelnasser, *et al*, “UbiBreathe: A Ubiquitous non-Invasive WiFi-based Breathing Estimator”, ACM MobiHoc, 2015
2. X.F. Liu, *et al*, “Contactless Respiration Monitoring Via Off-the-Shelf WiFi Devices”, IEEE Transaction on Mobile Computing, 2016
3. H. Wang, *et al*, “Human Respiration Detection with Commodity WiFi Devices: Do User Location and Body Orientation Matter?”, ACM UbiComp, 2016

# Related Work

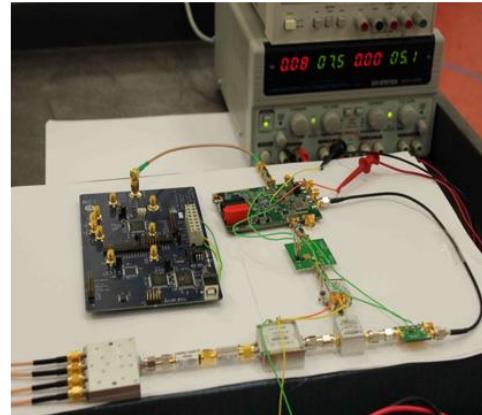
- **Research**

- **RF signal based respiration monitoring**
  - **FMCW (Frequency Modulated Carrier Waves) [4]**

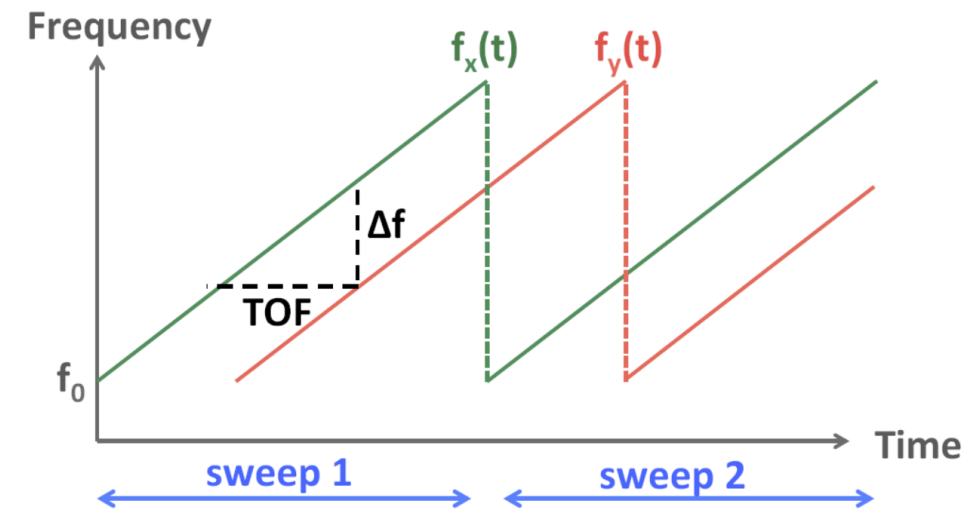
inhalation & exhalation  
 ↓  
 tiny chest movement  
 ↓  
 signal travelling distance change



**FMCW: linearly increased frequencies**



$$TOF = \Delta f / slope$$





## Limitation

- **Limitation for existing RF signal based methods**
  - **Low resolution** for WiFi system
  - **FMCW** systems require **customized active radio**, which are not readily available on the market.
  - Both systems may fail in detecting **multiple persons**

**A low cost, non-intrusive and convenient system that is able to detect breaths of multiple persons is needed !**



# Advantages of RFID systems

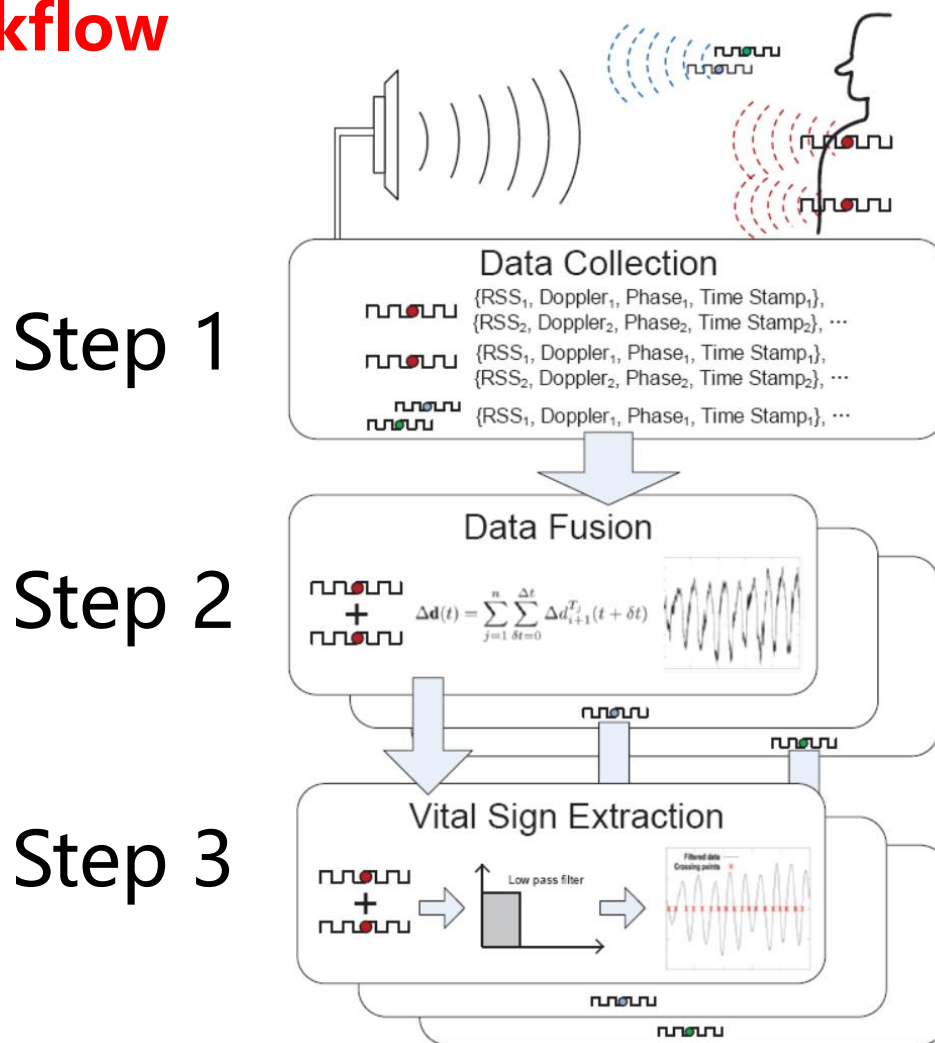
- **RFID based methods**
  - **Widespread use**
  - **Provides opportunities for **nonintrusive cost-effective** healthcare monitoring**
  - **High resolution of 0.038mm movement detection**
  - **Work for **multiple persons****



**\$5-10 cents each**

# The *TagBreathe* System

- TagBreathe workflow**



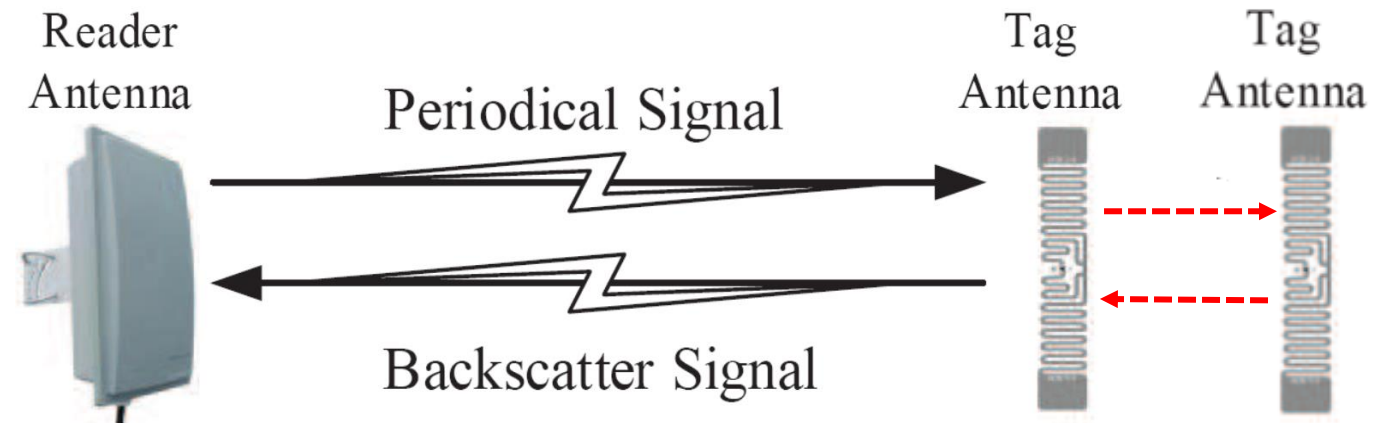
Monitor human  
breath rate

# Low Level Data of the Signal

## LOS

- **Low level data**

- ❖ **RSS (Received Signal Strength)**
- ❖ **DFS (Doppler Frequency Shift)**
- ❖ **SPV (Signal Phase Values)**



Due to the distance between tag and reader changes periodically, corresponding low level data also changes.



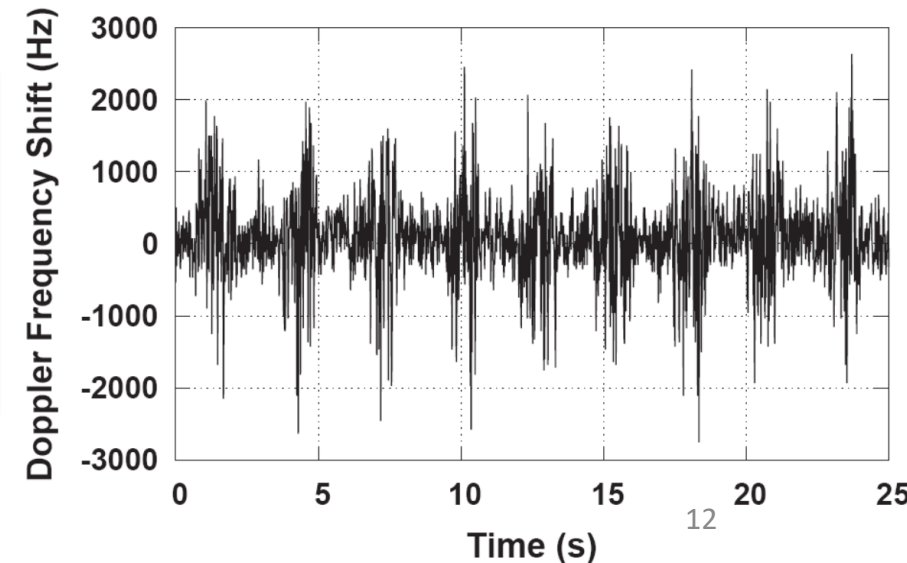
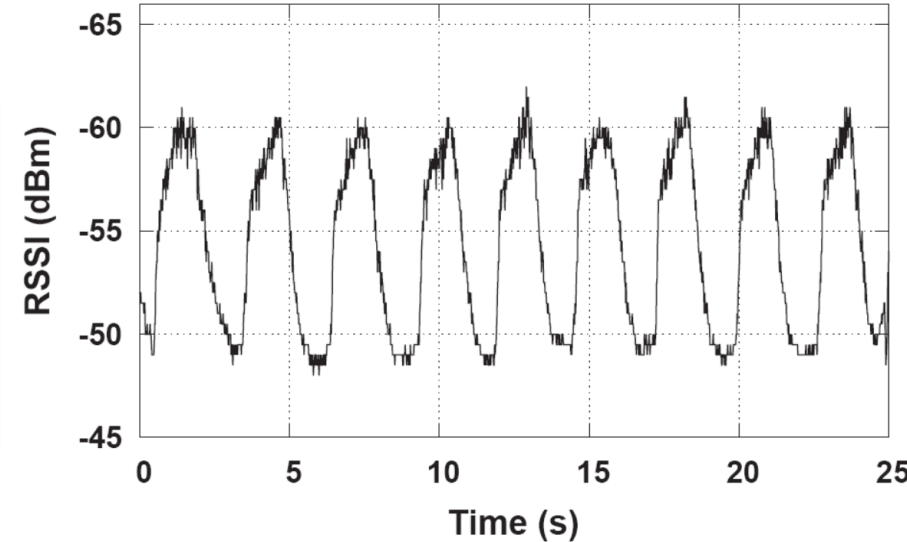
# The *TagBreathe* System

- Limitation of using RSS

- ❖ Low resolution
- ❖ Unavailable in more challenging working scenarios

- Limitation of using DFS

- ❖ *DFS* during the one packet transmission is not reliable and may be subject to noises in practice.
- ❖ More suitable for high speed movement of tags





## The *TagBreathe* System

- **Signal Phase Values**

- ❖ **High resolution of 0.038mm movement**

- ❖ **Suitable for both high and low speed movement**



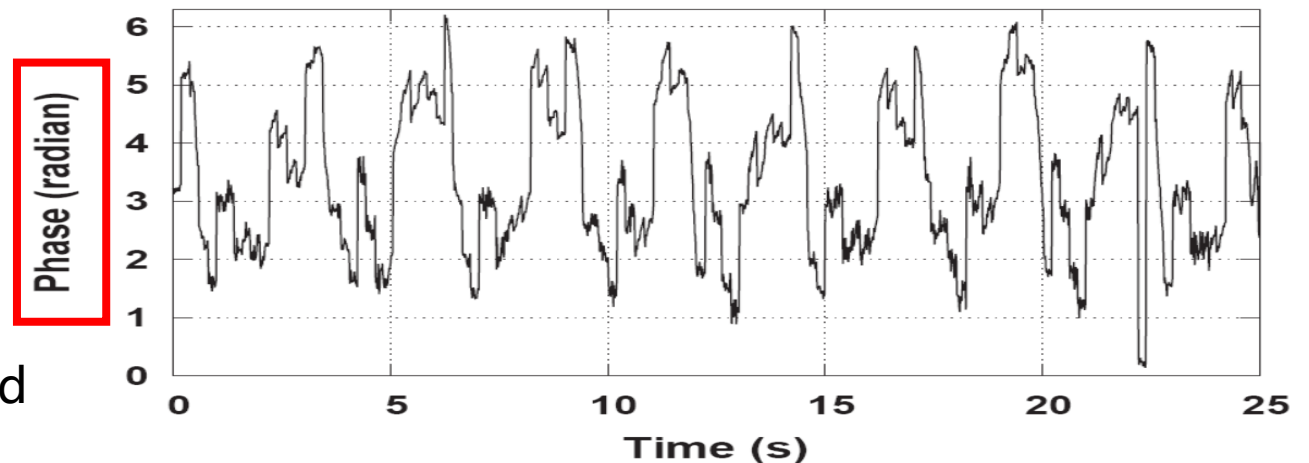
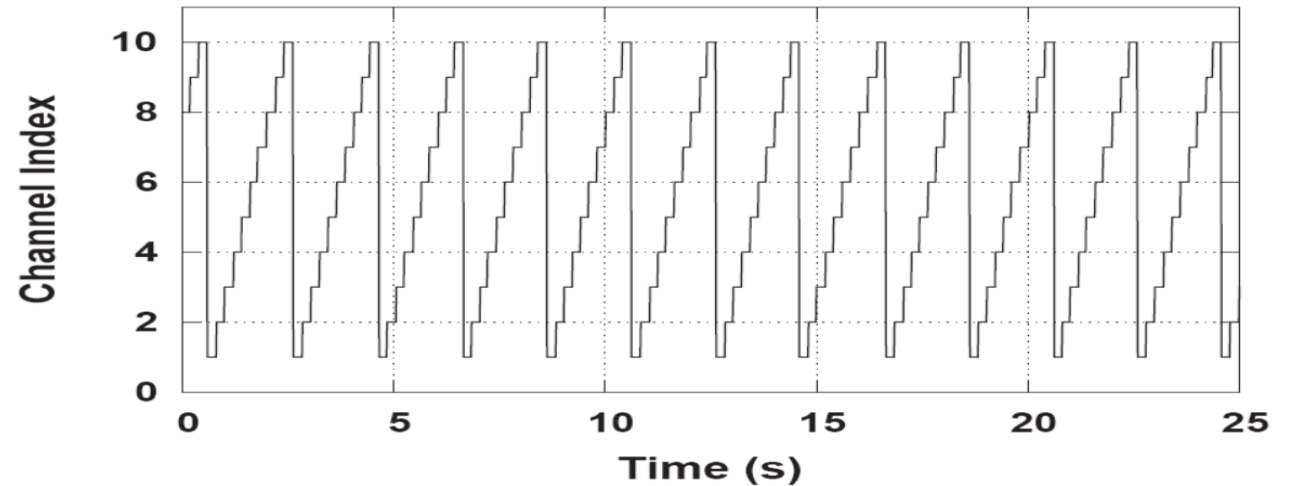
# The *TagBreathe* System

## • Challenge 1: Channel Frequency Hopping in standard EPC protocol

- ❖ 0.2 seconds for 1 channel
- ❖  $\lambda$  and the phase offset change
- ❖ Discontinuity of phase values for every 0.2s

$$\theta = \left( \frac{2\pi}{\lambda} \times 2d + \theta' \right) \bmod 2\pi$$

phase offset is caused by the circuits of reader and tag, which is independent of the distance





# The *TagBreathe* System

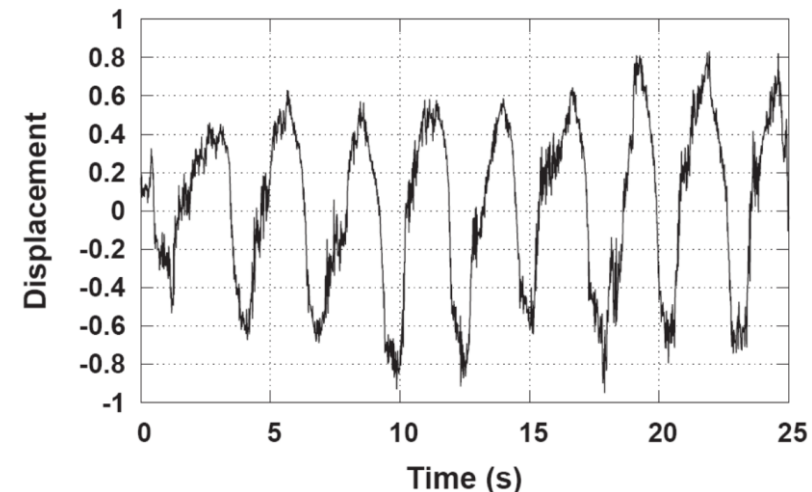
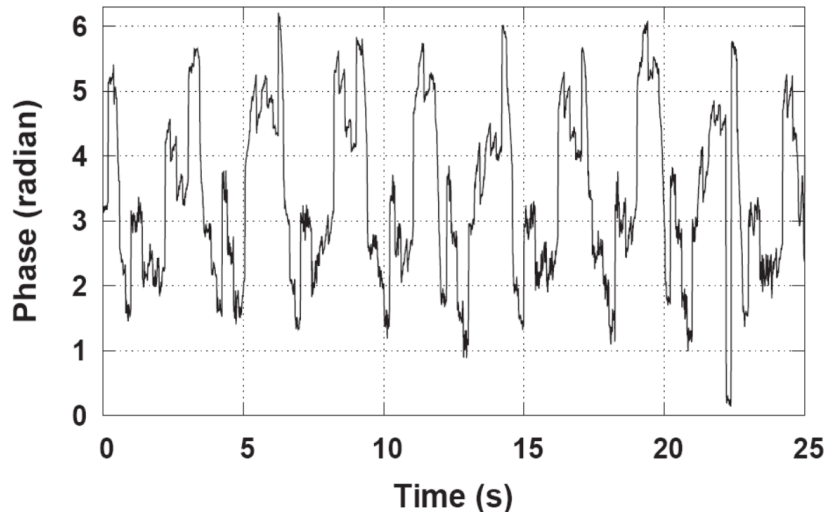
## • Challenge 1: Channel Frequency Hopping in standard EPC protocol

- (1) Group the phase values according to channel indexes.
- (2) Then, calculate the displacement during two consecutive phase readings **in the same channel** to eliminate phase offsets.

$$\Delta d_{i+1} = d_{i+1} - d_i = \frac{\lambda}{4\pi} (\theta_{i+1} - \theta_i)$$



$$D_j = \sum_{i=1}^N \Delta d_{i+j}$$



The displacement values are not influenced by the frequency hopping and track the periodic body movement mainly due to breathing !



# The *TagBreathe* System

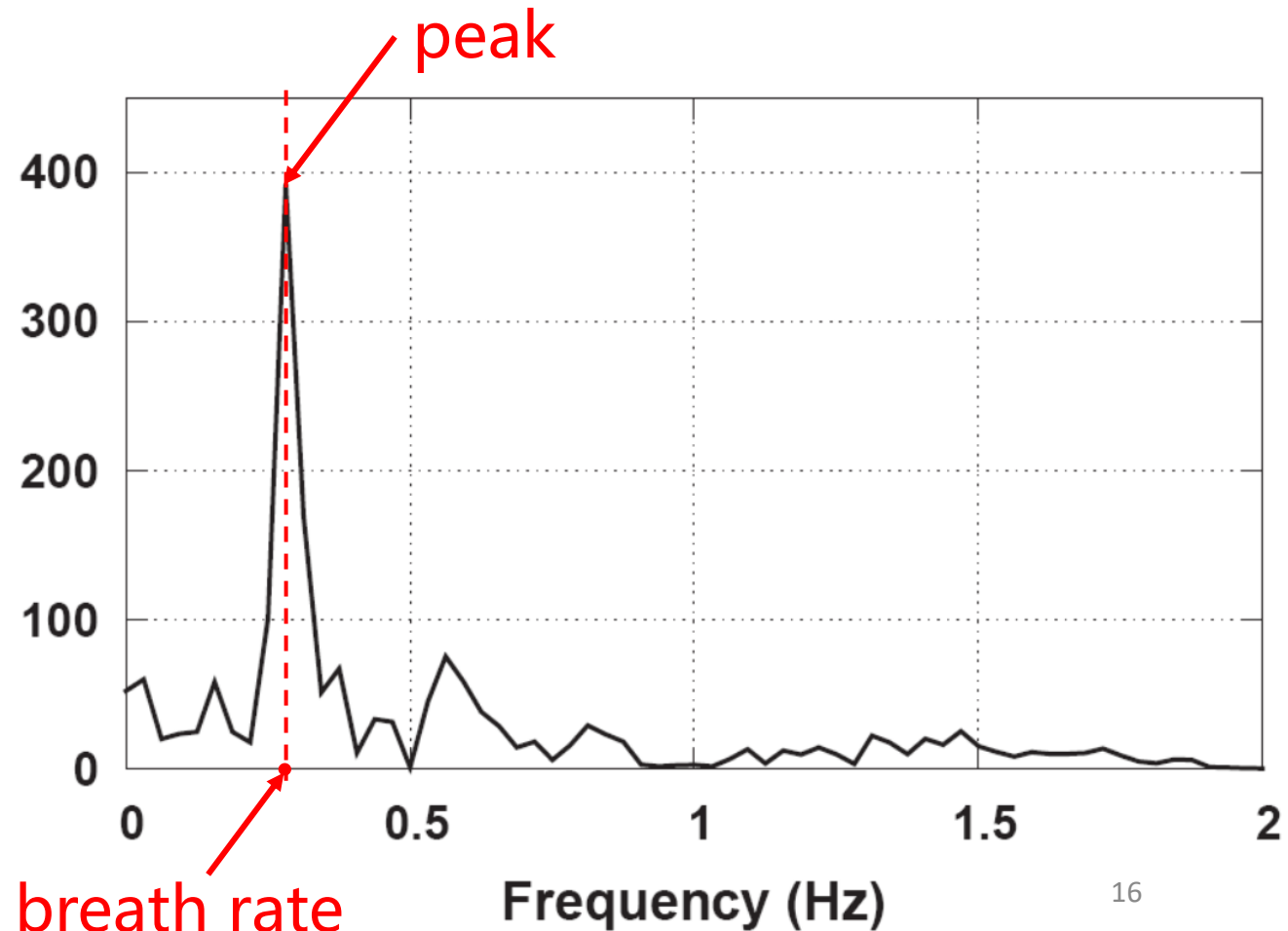
- **Challenge 2: Extract the breath pattern from the waveform**

FFT (Fast Fourier Transform)

The peak of the FFT output corresponds to the breathing rate.

The Fourier transform for a window size of  $w$  seconds is that it has a resolution of  $1/w$ .

In our initial experiment,  $w=25$ s, the frequency resolution is 0.04 Hz which corresponds to 2.4 breaths per minute.





# The *TagBreathe* System

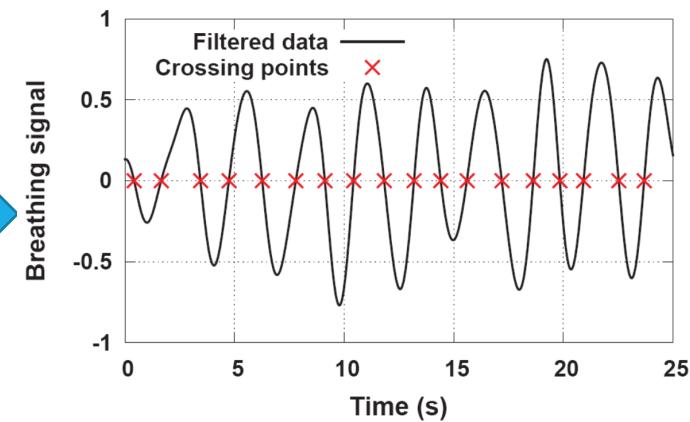
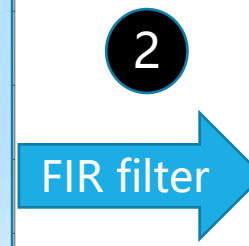
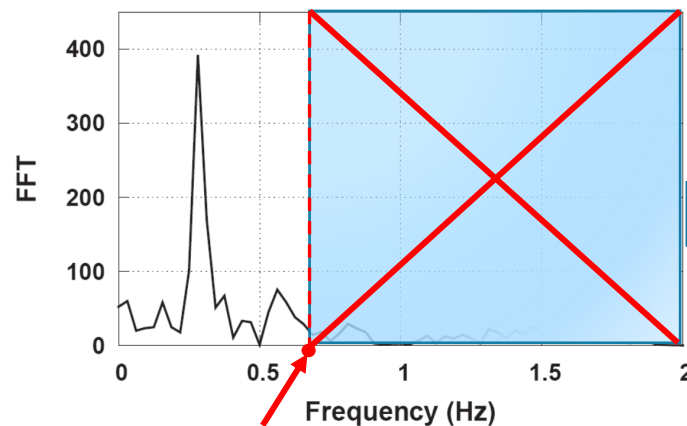
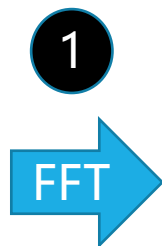
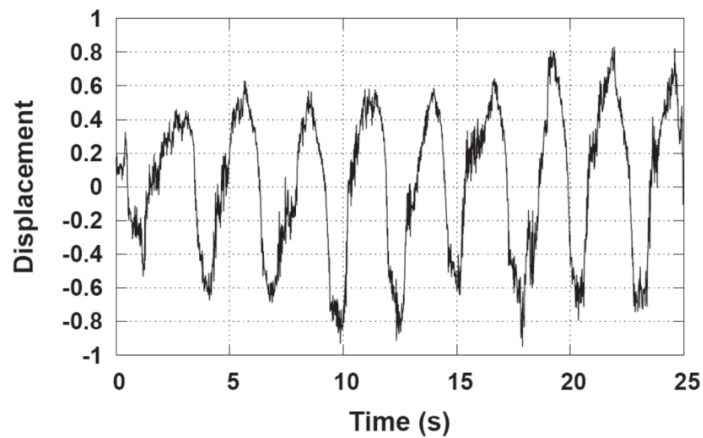
## • Challenge 2: Extract the breath pattern from the waveform

Apply an FFT-based low pass filter to filter out high frequency noises and then extract the breathing signals.

- ❖ Average 12 - 20 breaths per minute for a healthy person.
- ❖ Lower than 40 breaths per minute.



the cutoff frequency of the low pass filter = 0.67 Hz.



cutoff frequency  
=0.67Hz

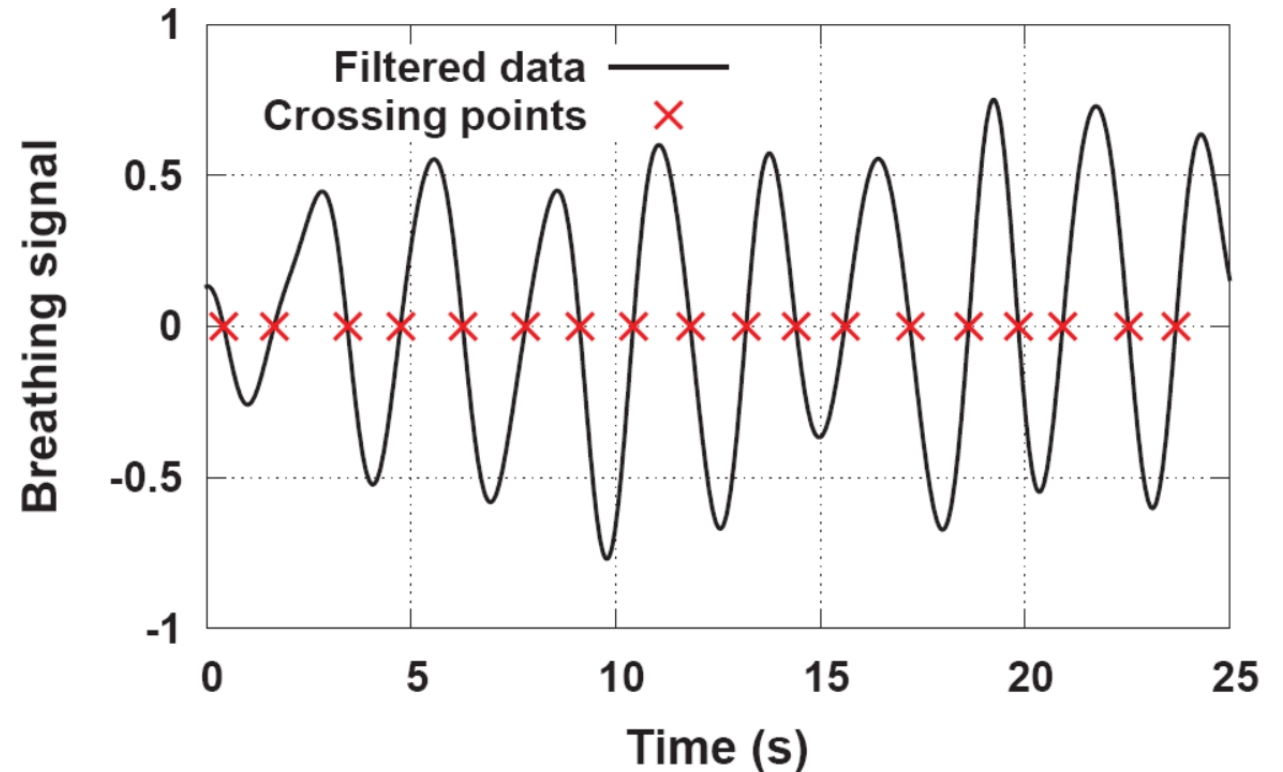


# The *TagBreathe* System

- **Challenge 2: Extract the breath pattern from the signal phase values**

Record the time stamps of the zero crossing events and calculate the instant breathing rate as:

1. Count the number of 0-crossing points  $M$  during  $\Delta t$
2. Breath rate =  $(M-1)/2\Delta t$



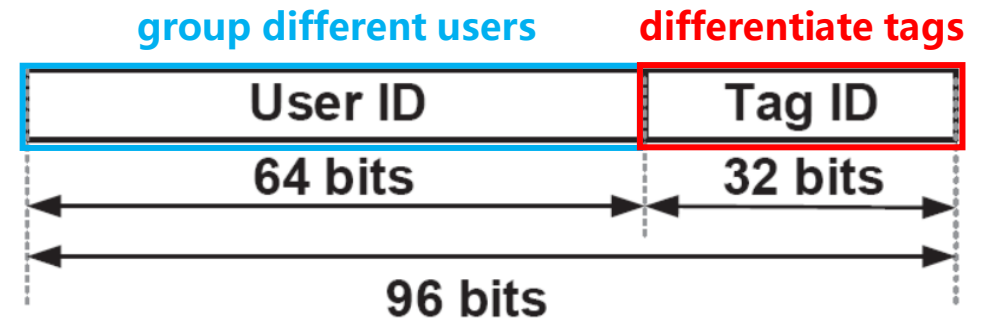


# The *TagBreathe* System

## • Challenge 3: Weak signals and NLOS

With **Sensor Fusion of Multiple Tags**, *TagBreathe* can effectively improve the performance by constructively add raw data, which substantially enhances signal extraction in case that **signals are weak or are blocked in LOS path**.

- ❖ *TagBreathe* overwrites 96-bit tag ID with 64-bit user ID and 32-bit short tag ID.
- ❖ We fuse the raw data before extracting breath signals. That is because it can effectively improve signal strength.



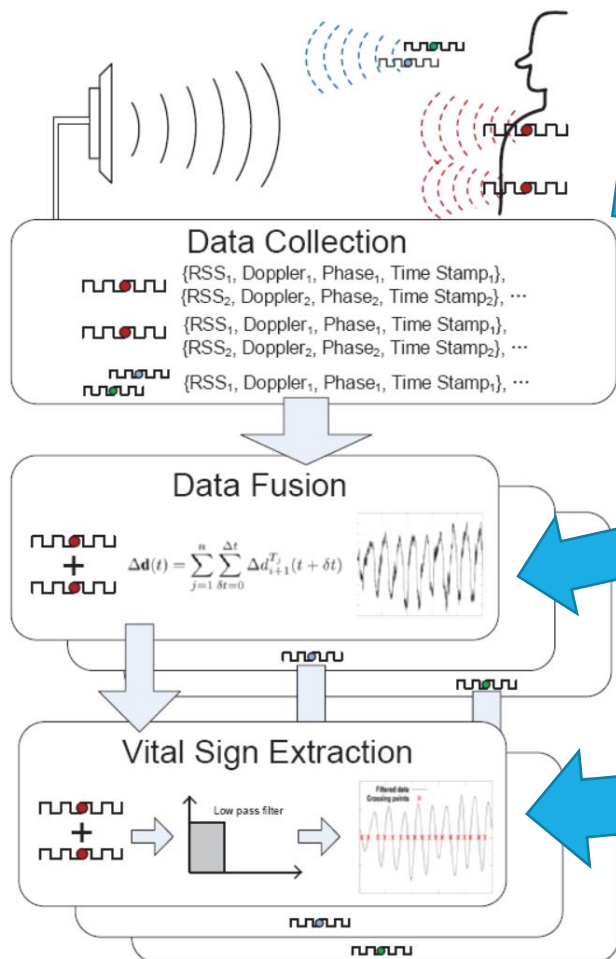
The displacement value for tag  $T_j$  collected during the time period  $[t, t + \Delta t]$  can be described as:

$T_j: Tag j, j \in [1, n]; \delta t \in [t, t + \Delta t]$

$$\Delta \mathbf{d}(t) = \sum_{j=1}^{\boxed{n}} \sum_{\delta t=0}^{\Delta t} \Delta d_{i+1}^{T_j}(t + \delta t) \longrightarrow \Delta \mathbf{D}(t) = \sum_{i=0}^{\boxed{N}} \Delta \mathbf{d}(t + i\Delta t)$$

# The *TagBreathe* System

## • *TagBreathe* workflow



*TagBreathe* interrogates multiple RFID tags attached to users and translate the phase value into distance.

$$\Delta d_{i+1} = d_{i+1} - d_i = \frac{\lambda}{4\pi} (\theta_{i+1} - \theta_i)$$

*TagBreathe* groups the readings and carries out raw data fusion by synthesizing multiple data streams

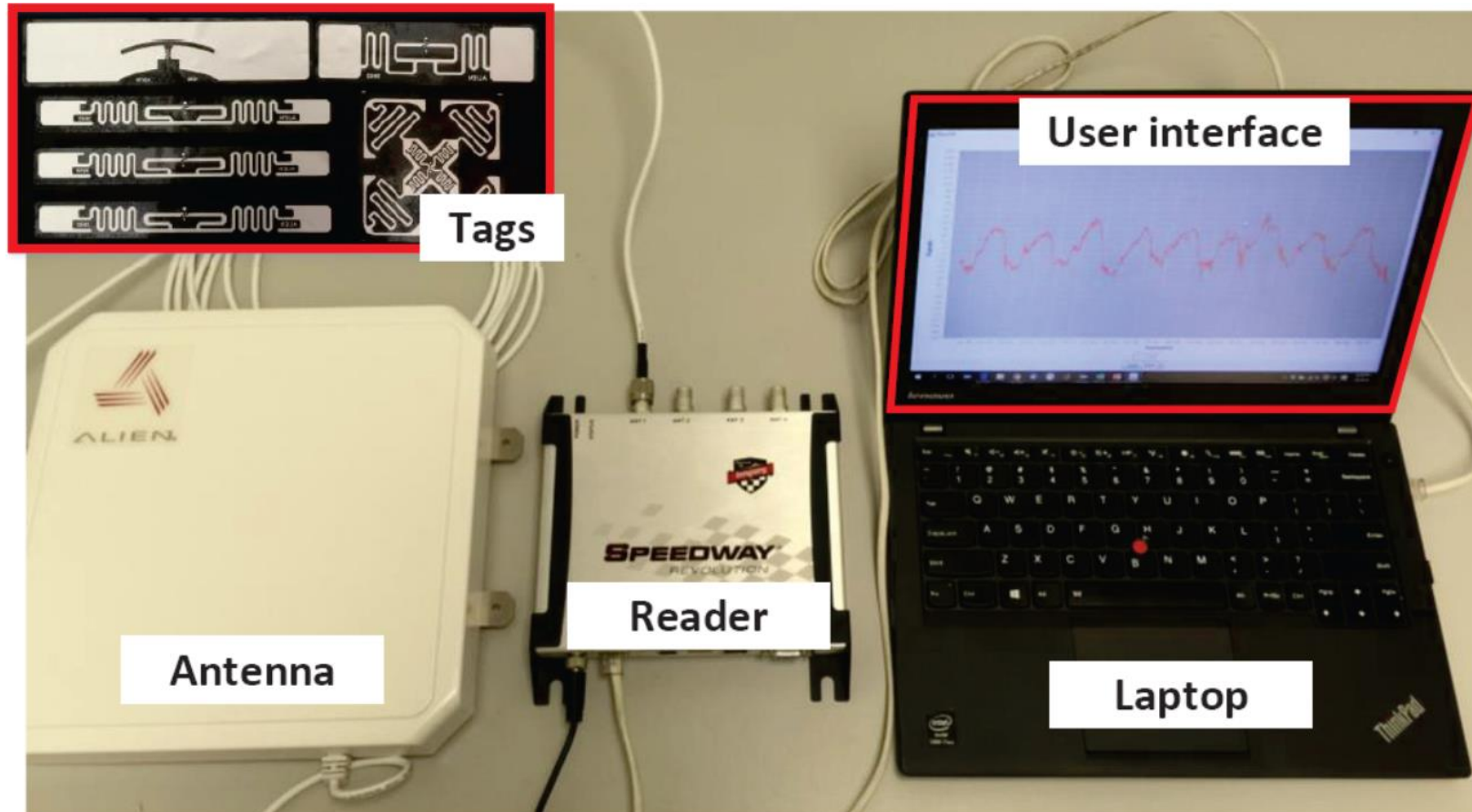
$$\Delta \mathbf{d}(t) = \sum_{j=1}^n \sum_{\delta t=0}^{\Delta t} \Delta d_{i+1}^{T_j}(t + \delta t)$$

*TagBreathe* analyzes the synthesized data stream and extracts breathing signals for each user

$$\overline{f_{BR}}(t_i) = \frac{M - 1}{2(t_i - t_{i-M})}$$

# Implementation

- **TagBreathe prototype system**



We perform a real-time and online implementation of TagBreathe prototype by using COTS RFID. 21



# Evaluation

## • Default Configuration

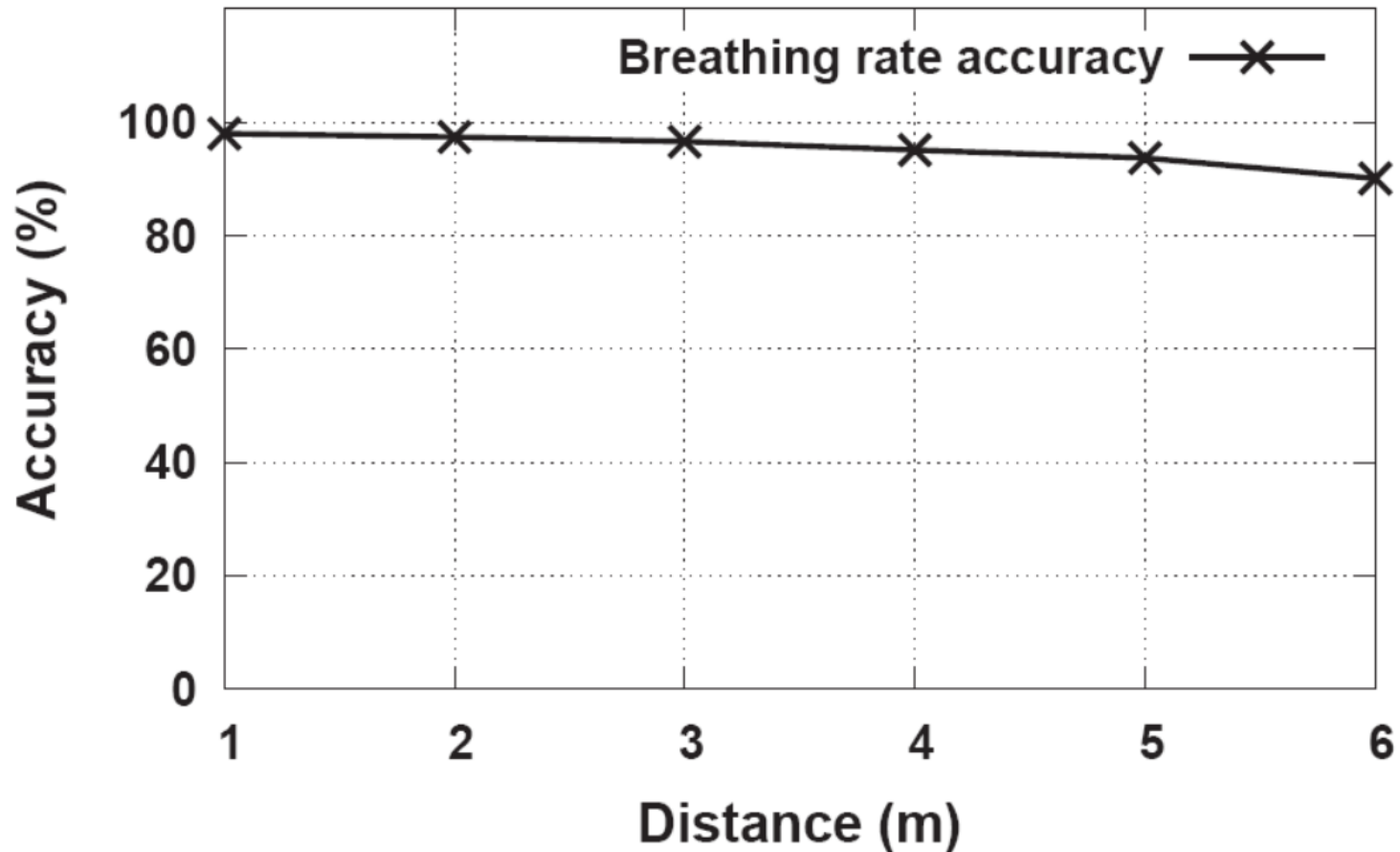
Table I  
SYSTEM PARAMETERS AND DEFAULT EXPERIMENT SETTINGS

Parameter	Range	Default
Channel	channel 1 - channel 10	Hopping
Tx power	15 - 30 dBm	30 dBm
Distance	1m - 6m	4m
Orientation	0° (front) - 180° (back)	front
Number of users	1 - 4 users	1 user
Tags per user	1 - 3 tags	3 tags
Breathing rate	5 - 20 bpm	10 bpm
Posture	Sitting, Standing, Lying	Sitting
Propagation path	with/without LOS path	with LOS path



# Evaluation

## • Evaluation Results

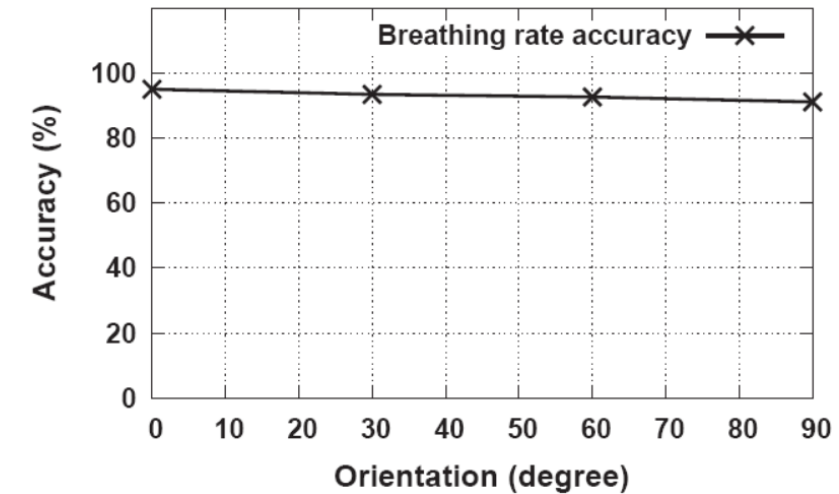
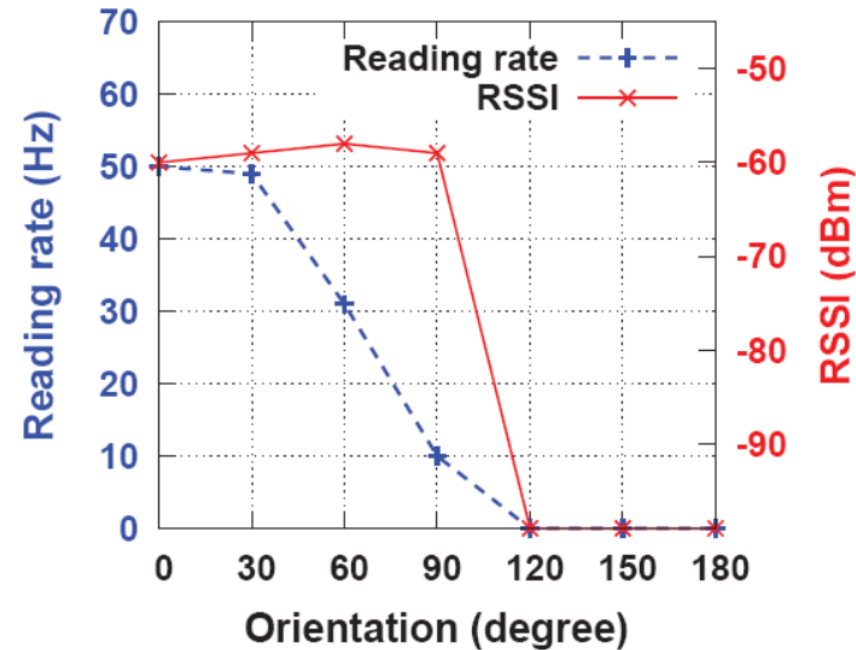
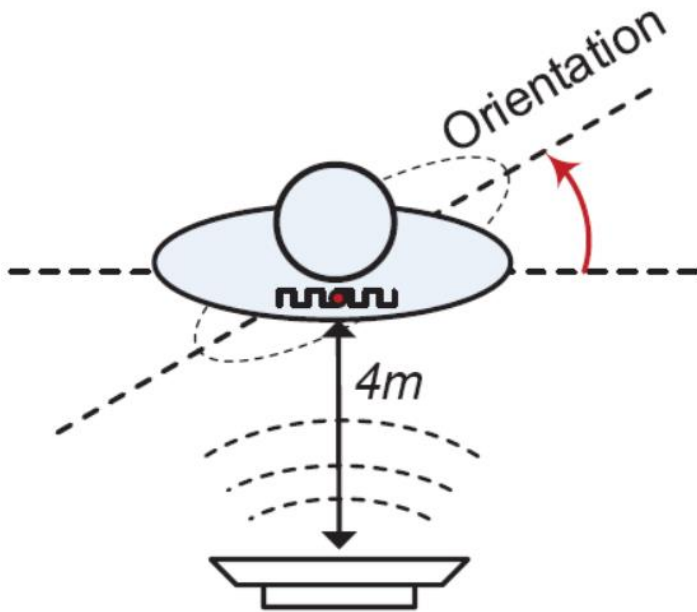


Breathing rate accuracy at different **distances**.

- ❖ The breathing rates range from 5 to 20 breaths per minute (bpm).
- ❖ Repeat the experiments for 100 times
- ❖ Each experiment lasts for two minutes.

# Evaluation

## • Evaluation Results



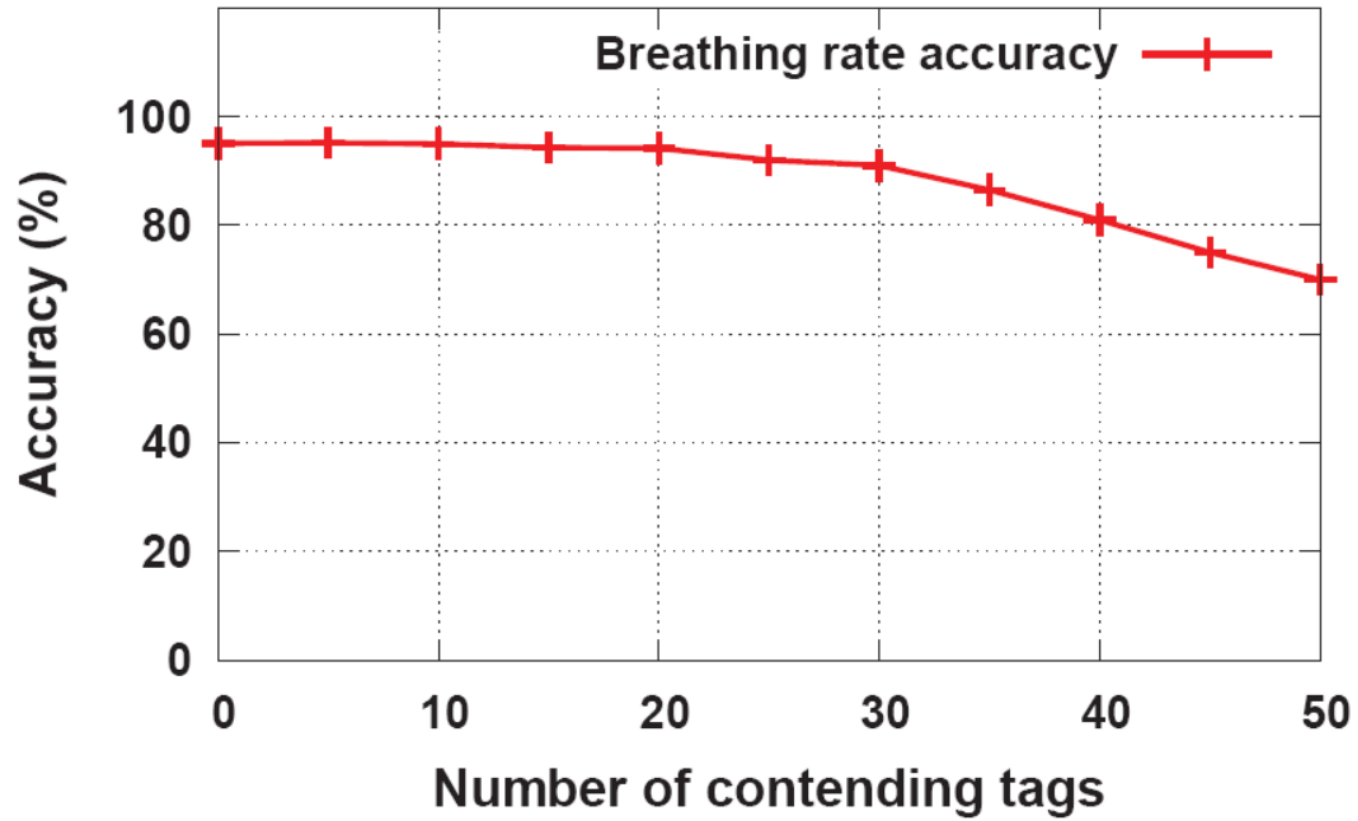
Reading rate and RSSI in different **orientation and accuracy**.





# Evaluation

- **Evaluation Results**

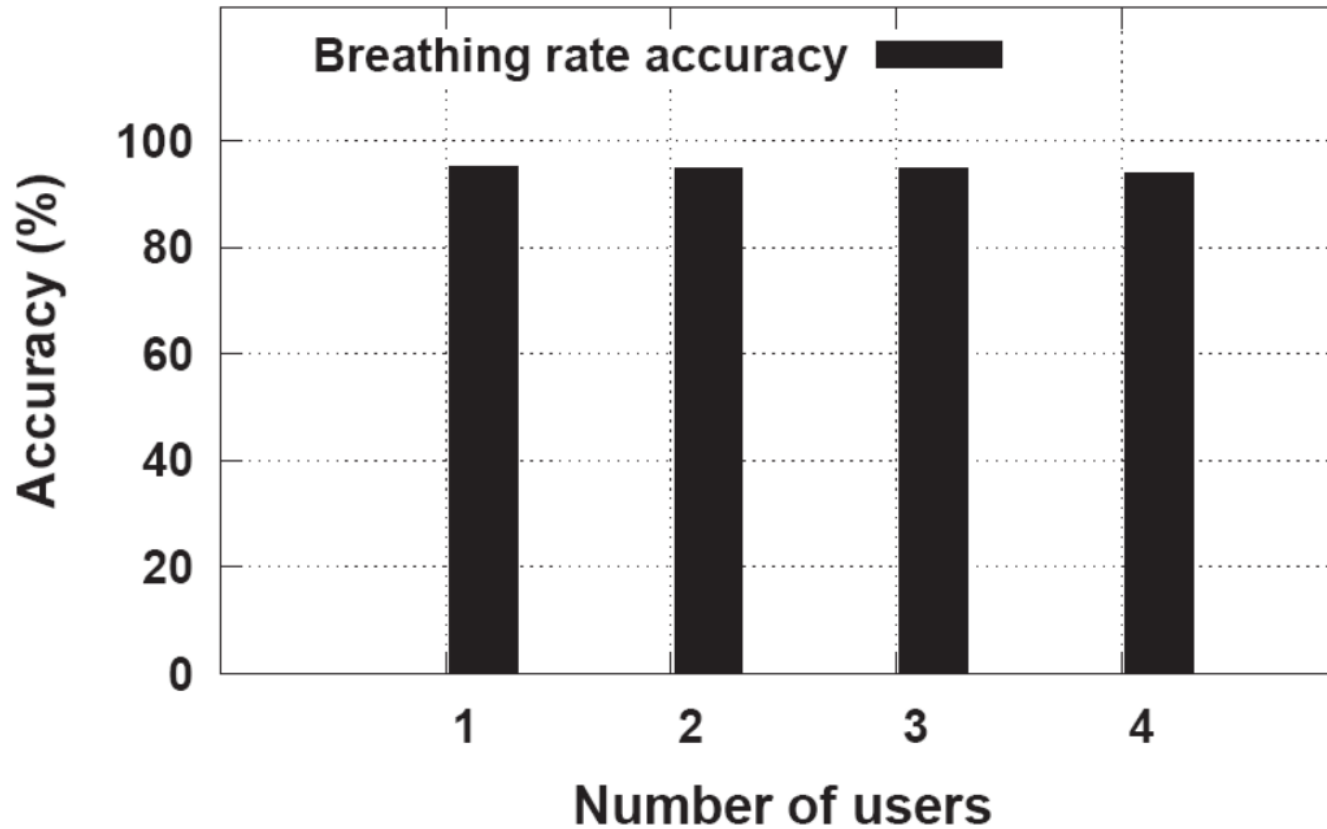


Breathing rate accuracy with different **# of tags**.



# Evaluation

- **Evaluation Results**



Breathing rate accuracy with different **# of users**.



## Conclusion

- ❖ We propose a low cost, non-intrusive COTS RFID system to monitor human breath.
- ❖ We carefully design sensor fusing algorithms to extract breathing signals from the low level data reported by commodity readers.
- ❖ *TagBreathe* can monitor breathing for multiple users



# Thanks!